

## CYCLOID MOTION IN CROSSED ELECTRIC AND MAGNETIC FIELDS

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Reference: Griffiths, David J. (2007) Introduction to Electrodynamics, 3rd Edition; Prentice Hall - Problem 5.2.

One of the classic examples of how mixing electric and magnetic fields can produce unusual results is the case of cycloid motion. The idea is that we have a constant magnetic field pointing in the  $x$  direction, and a constant electric field perpendicular to the magnetic field. We might as well align the electric field with the  $z$  axis.

If we place a particle with charge  $q$  at the origin and either give it an initial velocity perpendicular to  $\mathbf{B}$  or start it at rest, then neither the electric nor the magnetic field will exert a force in the  $x$  direction, so the motion is restricted entirely to the  $yz$  plane.

Combining the Lorentz force law  $\mathbf{F} = q\mathbf{v} \times \mathbf{B}$  and electrostatics with Newton's law  $\mathbf{F} = m\mathbf{a}$  we get, using a dot to denote a derivative w.r.t. time:

$$m\ddot{y} = qB\dot{z} \quad (1)$$

$$m\ddot{z} = qE - qB\dot{y} \quad (2)$$

At this point, we can note that it's quite easy to generalize this system so that  $\mathbf{E}$  has an arbitrary direction perpendicular to  $\mathbf{B}$ . However, there's not much point in doing so, since this amounts merely to a rotation of the coordinates about the  $x$  axis. Giving  $\mathbf{E}$  a component along  $x$ , however, *does* introduce significant complexity into the system, since we then have a force component along  $x$ , so we need another differential equation in the above set.

We can solve the system of 2 ODEs above by using software (or by hand, if you're familiar with methods of solving systems like this), and we get

$$y(t) = -\frac{c_3}{\omega} \cos \omega t + \frac{c_2}{\omega} \sin \omega t + \frac{E}{B}t + c_4 \quad (3)$$

$$z(t) = \frac{c_3}{\omega} \sin \omega t + \frac{c_2}{\omega} \cos \omega t + \frac{E}{\omega B} + c_1 \quad (4)$$

where  $\omega \equiv \frac{qB}{m}$  and the  $c_i$ s are constants of integration. Note that  $\omega$  has units of inverse time, as we can see from the Lorentz force law above.  $qB$

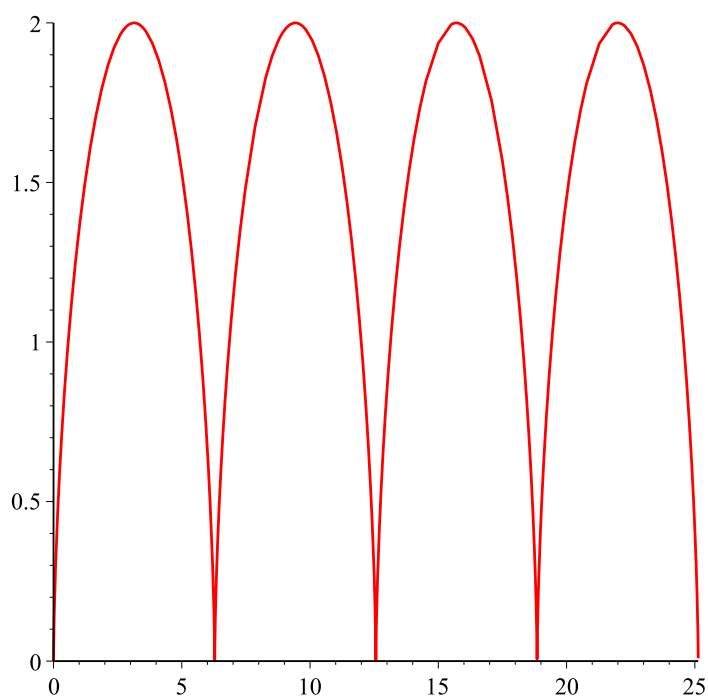
has units of force/velocity, which has units of mass  $\times$  time $^{-1}$ . (For those reading Griffiths's book, the constants in our solution can be redefined to produce Griffiths's equation 5.6, since  $E, B, q, m$  and  $\omega$  are all constants here.)

The four constants can be determined by specifying the initial position and velocity of the particle. If it starts at rest at the origin (that is,  $x(0) = y(0) = \dot{x}(0) = \dot{y}(0) = 0$ ), we can apply these conditions to the solution (again, using software to ease the mathematics), and get

$$y(t) = -\frac{E}{\omega B} \sin \omega t + \frac{E}{B} t \quad (5)$$

$$z(t) = -\frac{E}{\omega B} \cos \omega t + \frac{E}{\omega B} \quad (6)$$

These two equations give the trajectory in parametric form, so we can vary  $t$  to get a plot of  $z$  versus  $y$  (we've taken all the constants to be 1  $E = B = q = m = 1$  for convenience):



Taking an initial velocity of  $\frac{E}{B}$  along the  $y$  axis ( $\dot{y}(0) = \frac{E}{B}$ ), we get

$$y(t) = \frac{E}{B} t \quad (7)$$

$$z(t) = 0 \quad (8)$$

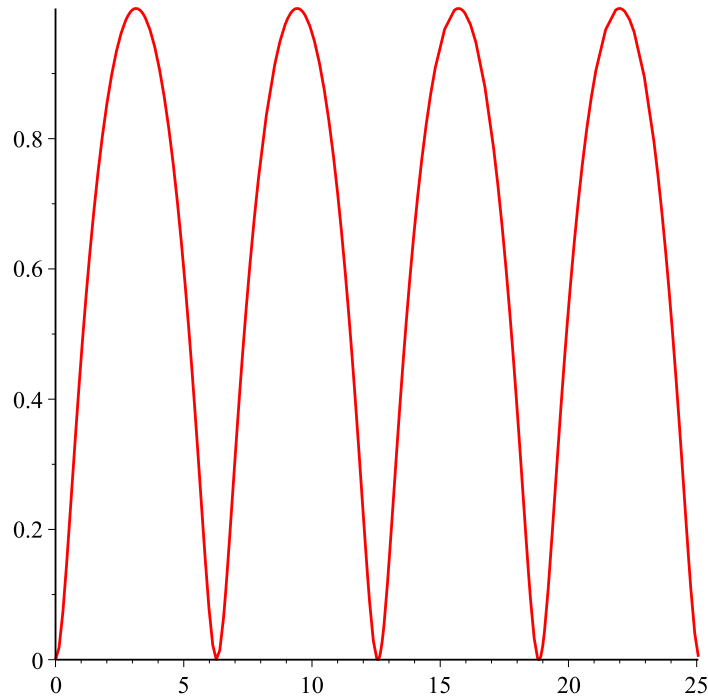
In this case the particle moves at constant speed along the  $y$  axis. Why? The electric force is  $qE$  in the  $+z$  direction (assuming  $q$  is positive), and the initial magnetic force is  $qvB = q\frac{E}{B}B = qE$  in the  $-z$  direction (use the right hand rule in the cross product). Thus the two forces cancel each other, so there is no net acceleration and the initial velocity remains unchanged.

If  $\dot{y}(0) = \frac{E}{2B}$ , we get

$$y(t) = -\frac{E}{2\omega B} \sin \omega t + \frac{E}{B}t \quad (9)$$

$$z(t) = -\frac{E}{2\omega B} \cos \omega t + \frac{E}{2\omega B} \quad (10)$$

This gives a similar trajectory to the first example, but with a reduced amplitude:

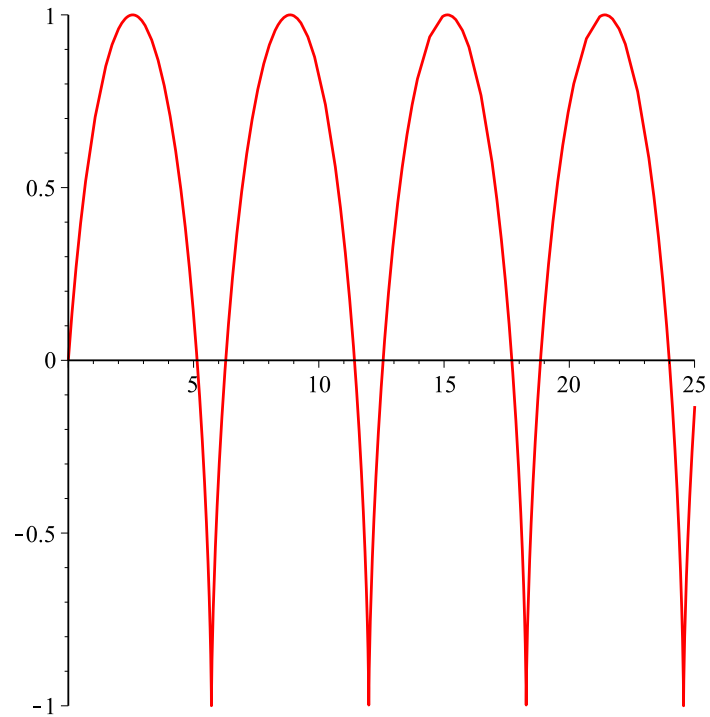


Finally, if we start the particle off travelling at an angle of  $\pi/4$  w.r.t. the  $y$  axis, so that  $\dot{y}(0) = \dot{z}(0) = \frac{E}{B}$ , we get

$$y(t) = -\frac{E}{\omega B} \cos \omega t + \frac{E}{B}t + \frac{E}{\omega B} \quad (11)$$

$$z(t) = \frac{E}{\omega B} \sin \omega t \quad (12)$$

This gives a trajectory identical in shape to the first case, but shifted down so that its midpoint is now on the y axis:



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