

## TORQUE ON A MAGNETIC MOMENT; GENERAL CURRENT DISTRIBUTION

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References: Griffiths, David J. (2007) Introduction to Electrodynamics, 3rd Edition; Prentice Hall - Problem 6.2.

Jackson, J. D. (1999) Classical Electrodynamics, 3rd Edition; Wiley - Sections 5.6 and 5.7.

The torque on a square current loop in a constant, uniform magnetic field is given by

$$(0.1) \quad \mathbf{N} = \mathbf{m} \times \mathbf{B}$$

It turns out that this formula applies to any current distribution, although the proof is a bit tricky. Since the magnetic moment for a collection of line currents is defined as

$$(0.2) \quad \mathbf{m} = I \mathbf{a} = \frac{1}{2} I \int \mathbf{r} \times d\mathbf{l}$$

the natural generalization of magnetic moment to a general volume current density is

$$(0.3) \quad \mathbf{m} = \frac{1}{2} \int \mathbf{r} \times \mathbf{J} d^3\mathbf{r}$$

The Lorentz force law for a volume current is

$$(0.4) \quad \mathbf{F} = \int \mathbf{J} \times \mathbf{B} d^3\mathbf{r}$$

so the torque is

$$(0.5) \quad \mathbf{N} = \int \mathbf{r} \times (\mathbf{J} \times \mathbf{B}) d^3\mathbf{r}$$

We can convert this using a vector identity:

$$(0.6) \quad \mathbf{N} = \int (\mathbf{r} \cdot \mathbf{B}) \mathbf{J} d^3\mathbf{r} - \int (\mathbf{r} \cdot \mathbf{J}) \mathbf{B} d^3\mathbf{r}$$

To proceed further, we need another vector identity, which states that for scalar fields  $f$  and  $g$  and localized vector field  $\mathbf{J}$ , we have

$$(0.7) \quad \int [f\mathbf{J} \cdot \nabla g + g\mathbf{J} \cdot \nabla f + fg\nabla \cdot \mathbf{J}] d^3\mathbf{r} = 0$$

This follows, since if we integrate the middle term by parts, we get

$$(0.8) \quad \int g\mathbf{J} \cdot \nabla f = fg(J_x + J_y + J_z) - \int f\nabla \cdot (g\mathbf{J}) d^3\mathbf{r}$$

$$(0.9) \quad = 0 - \int [f\mathbf{J} \cdot \nabla g + fg\nabla \cdot \mathbf{J}] d^3\mathbf{r}$$

where the integrated term is zero if we assume that  $\mathbf{J}$  goes to zero at infinity (that is, it's localized).

Now if we consider steady currents, then  $\nabla \cdot \mathbf{J} = 0$  so the identity reduces to

$$(0.10) \quad \int [f\mathbf{J} \cdot \nabla g + g\mathbf{J} \cdot \nabla f] d^3\mathbf{r} = 0$$

If we take  $f = g = r = \sqrt{x^2 + y^2 + z^2}$ , then  $\nabla r = \mathbf{r}/r$  and

$$(0.11) \quad 2 \int r\mathbf{J} \cdot \frac{\mathbf{r}}{r} d^3\mathbf{r} = 2 \int \mathbf{r} \cdot \mathbf{J} d^3\mathbf{r} = 0$$

so the second integral in the torque 0.6 is zero (remember  $\mathbf{B}$  is constant, so it comes outside the integral).

For the first term, we use the identity with  $f = x$ ,  $g = y$ :

$$(0.12) \quad \int (xJ_y + yJ_x) d^3\mathbf{r} = 0$$

Choosing the other coordinates in turn, we have in general for  $i$  and  $j$  equal to any combination of  $x$ ,  $y$  and  $z$ :

$$(0.13) \quad \int (r_i J_j + r_j J_i) d^3\mathbf{r} = 0$$

Now look at the  $i$ th component of the first term of 0.6:

$$(0.14) \quad N_i = \int (\mathbf{r} \cdot \mathbf{B}) J_i d^3 \mathbf{r}$$

$$(0.15) \quad = \sum_j B_j \int r_j J_i d^3 \mathbf{r}$$

$$(0.16) \quad = \frac{1}{2} \sum_j B_j \int (r_j J_i - r_i J_j) d^3 \mathbf{r}$$

where we used 0.13 to get the last line.

If we take  $i = x$  for example, we get

$$(0.17) \quad N_x = \frac{1}{2} B_y \int (y J_x - x J_y) d^3 \mathbf{r} + \frac{1}{2} B_z \int (z J_x - x J_z) d^3 \mathbf{r}$$

$$(0.18) \quad = \frac{1}{2} \int [ -(\mathbf{r} \times \mathbf{J})_z B_y + (\mathbf{r} \times \mathbf{J})_y B_z ] d^3 \mathbf{r}$$

$$(0.19) \quad = \frac{1}{2} \left[ \left( \int \mathbf{r} \times \mathbf{J} d^3 \mathbf{r} \right) \times \mathbf{B} \right]_x$$

The other two components work out similarly, so we get

$$(0.20) \quad \mathbf{N} = \left[ \frac{1}{2} \int \mathbf{r} \times \mathbf{J} d^3 \mathbf{r} \right] \times \mathbf{B}$$

$$(0.21) \quad = \mathbf{m} \times \mathbf{B}$$

I suspect this isn't the way Griffiths meant this problem to be solved, since he deals only with line currents, but this is a more general proof anyway.