

## LINEAR MAPS, LINEAR OPERATORS AND COMMUTATORS

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### 1. LINEAR MAPS

Having looked at some of the properties of a vector space, we can now look at *linear maps*. A linear map  $T$  is defined as a function that maps one vector space  $V$  into another (possibly the same) vector space  $W$ , written as

$$T : V \rightarrow W \quad (1)$$

The linear map  $T$  must satisfy the two properties

- (1) **Additivity:**  $T(u+v) = Tu + Tv$  for all  $u, v \in V$ .
- (2) **Homogeneity:**  $T(\lambda v) = \lambda(Tv)$  for all  $\lambda \in \mathbb{F}$  and all  $v \in V$ . As usual, the field  $\mathbb{F}$  is either the set of real  $\mathbb{R}$  or complex numbers  $\mathbb{C}$ .

This definition of a linear map is general in the sense that the two vector spaces  $V$  and  $W$  can be any two vector spaces. In physics, it's more common to have  $V = W$ , and in such a case, the linear map  $T$  is called a *linear operator*.

### 2. LINEAR OPERATORS

With a couple of extra definitions, the set  $\mathcal{L}(V)$  of all linear operators on  $V$  is itself a vector space, with the operators being the vectors. In order for this to be true, we need the following:

- (1) **Zero operator:** A zero operator, written as just  $0$  (the same symbol now being used for three distinct objects: the scalar  $0$ , the vector  $0$  and the operator  $0$ ; again the correct meaning is usually easy to deduce from the context) which has the property that the result of acting with  $0$  on any vector produces the  $0$  vector. That is  $0v = 0$ , where the  $0$  on the LHS is the zero operator and the  $0$  on the RHS is the zero vector.
- (2) **Identity operator:** An identity operator  $I$  (sometimes written as  $1$ ) leaves any vector unchanged, so that  $Iv = v$  for all  $v \in V$ .

With these definitions,  $\mathcal{L}(V)$  is now a vector space, since it satisfies the distributive (additivity) and scalar multiplication (homogeneity) properties,

contains an additive identity (the zero operator) and a multiplicative identity (the identity operator).

In addition, there is a natural definition of the multiplication of two linear operators  $S$  and  $T$ , written as  $ST$ . When a product operates on a vector  $v \in V$ , we just operate from right to left (not left to right!) in succession, so that

$$(ST)v = S(Tv) \quad (2)$$

The product of two operators produces another operator also in  $\mathcal{L}(V)$ , since this product also satisfies additivity and homogeneity:

$$(ST)(u + v) = S(T(u + v)) \quad (3)$$

$$= S(Tu + Tv) \quad (4)$$

$$= STu + STv \quad (5)$$

$$(ST)(\lambda v) = S(T(\lambda v)) \quad (6)$$

$$= S(\lambda Tv) \quad (7)$$

$$= \lambda S(Tv) \quad (8)$$

$$= \lambda(ST)v \quad (9)$$

A very important property of operator multiplication is that it is not necessarily commutative. In quantum mechanics, for example, the position and momentum operators do not commute. The non-commutativity is a fundamental mathematical property however, and can be seen in other examples that have nothing to do with quantum theory.

For example, consider the left shift operator  $L$  and right shift operator  $R$ , defined to act on the vector space consisting of infinite sequences of numbers. That is, our vector space  $V$  is such that

$$v = (x_1, x_2, x_3, \dots) \quad (10)$$

where  $x_i \in \mathbb{F}$ . The shift operators have the following effects:

$$Lv = (x_2, x_3, \dots) \quad (11)$$

$$Rv = (0, x_1, x_2, x_3, \dots) \quad (12)$$

The  $L$  operator removes the first element in the sequence, while the  $R$  operator inserts a 0 (number!) as the new first element in the sequence. Note that 0 is the only number we could insert into a sequence in order that  $R$  be a linear operator, since from additivity above, we must have  $R0 = 0$ . That is, if we start with  $v = 0$  (the vector all of whose elements  $x_i = 0$ ), then  $R0$  must also give the zero vector.

The two products  $LR$  and  $RL$  produce different results:

$$LRv = L(0, x_1, x_2, x_3, \dots) = (x_1, x_2, x_3, \dots) = v \quad (13)$$

$$RLv = R(x_2, x_3, \dots) = (0, x_2, x_3, \dots) \neq v \quad (14)$$

### 3. COMMUTATORS

The difference  $[L, R] \equiv LR - RL$  is called the *commutator* of the two operators  $L$  and  $R$ . For example, if we introduce the operator which projects out the first element in the sequence:

$$P_1v \equiv P_1(x_1, x_2, x_3, \dots) = (x_1, 0, 0, \dots) \quad (15)$$

$$Iv - P_1v = (x_1, x_2, x_3, \dots) - (x_1, 0, 0, \dots) \quad (16)$$

$$= (0, x_2, x_3, \dots) = RLv \quad (17)$$

then we have

$$[L, R]v = Iv - (Iv - P_1v) \quad (18)$$

$$= P_1v \quad (19)$$

so that the commutator  $[L, R]$  projects out the first element of a vector.

### REFERENCES

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