

## METRIC TENSOR: SEMI-LOG COORDINATES

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Reference: Moore, Thomas A., *A General Relativity Workbook*, University Science Books (2013) - Chapter 5; Problem 5.4.

As an example of a different coordinate system, we can define the semi-log system by introducing coordinates  $p$  and  $q$  defined as:

$$\begin{aligned} (1) \quad & p = x \\ (2) \quad & q = e^{by} \end{aligned}$$

where  $b$  is a constant. If  $x$  and  $y$  have units of length, then  $b$  must have units of  $\text{length}^{-1}$ . Note that this means that  $p$  and  $q$  have different units, with  $p$  having the units of length and  $q$  being dimensionless.

The curves of constant  $p$  are just the same as the curves of constant  $x$ , that is, vertical lines. The curves of constant  $q$  are defined by  $e^{by} = k$  or  $y = \frac{\ln k}{b}$ . These are horizontal lines, although the spacing for equal steps in  $k$  will translate into the variable spacing seen on semi-log plots.

If an object has an acceleration  $\mathbf{a} = a^i$  in the rectangular system, then we can find its acceleration in the semi-log system in the usual way.

$$(3) \quad a^p = \frac{\partial p}{\partial x} a^x + \frac{\partial p}{\partial y} a^y$$

$$(4) \quad = a^x$$

$$(5) \quad a^q = \frac{\partial q}{\partial x} a^x + \frac{\partial q}{\partial y} a^y$$

$$(6) \quad = b e^{by} a^y$$

The units of  $a^p$  are still those of acceleration, but the units of  $a^q$  are  $\text{length}^{-1} \cdot \text{acceleration}$ .

We can work out the metric of the semi-log system from the rectangular metric by direct calculation:

$$(7) \quad g'_{ij} = g_{kl} \frac{\partial x^k}{\partial x'^i} \frac{\partial x^l}{\partial x'^j} = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{(bq)^2} \end{bmatrix}$$

The length squared of  $\mathbf{a}$  is an invariant, since

$$(8) \quad a^2 = g'_{ij} a^i a^j$$

$$(9) \quad = (a^x)^2 + \left(\frac{1}{bq}\right)^2 (be^{by} a^y)^2$$

$$(10) \quad = (a^x)^2 + (a^y)^2$$

The basis vectors in the semi-log system have lengths obtainable from the the metric:

$$(11) \quad \mathbf{e}_p \cdot \mathbf{e}_p = g_{pp} = 1$$

$$(12) \quad |\mathbf{e}_p| = 1$$

$$(13) \quad \mathbf{e}_q \cdot \mathbf{e}_q = g_{qq} = \frac{1}{(bq)^2}$$

$$(14) \quad |\mathbf{e}_q| = \frac{1}{bq}$$

Incidentally, the question part (e) as written in Moore's book doesn't make sense; he asks for the length of the basis vector  $\partial x$ . If we want to use partial derivatives as basis vectors, we need to define a curve along which to take the derivative. Since Moore doesn't even mention the use of partial derivatives as a basis in the text, I can only assume this is a typo.

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