

BOYER-LINDQUIST COORDINATES AND CURVATURE OF SPACE

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In Appendix I.5.2 of Zee's book, he discusses a modification of the spherical coordinate metric in flat space with the definitions

$$\begin{aligned}x &= f(r) \sin \theta \cos \phi \\y &= f(r) \sin \theta \sin \phi \\z &= r \cos \theta\end{aligned}\tag{1}$$

where $f(r)$ is some function to be specified.

We can write the usual Euclidean metric in terms of these new coordinates by finding the differentials:

$$\begin{aligned}dx &= f'(r) \sin \theta \cos \phi dr + f(r) \cos \theta \cos \phi d\theta - f(r) \sin \theta \sin \phi d\phi \\dy &= f'(r) \sin \theta \sin \phi dr + f(r) \cos \theta \sin \phi d\theta + f(r) \sin \theta \cos \phi d\phi \\dz &= -r \sin \theta d\theta\end{aligned}\tag{2}$$

We can now write the distance element by calculating (using Maple to simplify things):

$$\begin{aligned}ds^2 &= dx^2 + dy^2 + dz^2 \\&= (f'^2 \sin^2 \theta + \cos^2 \theta) dr^2 + (f^2 \cos^2 \theta + r^2 \sin^2 \theta) d\theta^2 + \\&\quad f^2 \sin^2 \theta d\phi^2 + 2(f f' - r) \sin \theta \cos \theta dr d\theta\end{aligned}\tag{3}$$

With an arbitrary f , this metric is rather ugly in that it's not even diagonal due to the presence of the $dr d\theta$ term. We can get rid of this term by choosing

$$f f' = r\tag{5}$$

which gives us

$$f df = r dr\tag{6}$$

which integrates to give

$$f^2 = r^2 + a^2 \quad (7)$$

where a is a constant of integration.

With this substitution, the metric becomes (again, after simplifying with Maple):

$$ds^2 = \frac{r^2 + a^2 \cos^2 \theta}{a^2 + r^2} dr^2 + (r^2 + a^2 \cos^2 \theta) d\theta^2 + (r^2 + a^2) \sin^2 \theta d\phi^2 \quad (8)$$

This description of flat space is known as the Boyer-Linquist coordinate system. Choosing $a = 0$ restores the standard spherical coordinate system, since then $f = r$.

In exercise I.5.4 of Zee's book, we are given the metric (note that the equation in Zee's book is missing a factor of $\sin^2 \theta$):

$$ds^2 = \frac{\rho^2}{\rho^2 + a^2 \sin^2 \theta} dr^2 + \rho^2 d\theta^2 + (r^2 + a^2) \sin^2 \theta d\phi^2 \quad (9)$$

This is the same metric as 8, with

$$\rho^2 = r^2 + a^2 \cos^2 \theta \quad (10)$$

We have

$$x = \sqrt{r^2 + a^2} \sin \theta \cos \phi \quad (11)$$

$$y = \sqrt{r^2 + a^2} \sin \theta \sin \phi \quad (12)$$

$$z = r \cos \theta \quad (13)$$

For $a \neq 0$, if we set $r = 0$ then $z = 0$ so we're restricted to the xy plane. However, we still have a range of values possible for x and y , so $r = 0$ describes a disc rather than a single point. For a fixed value of θ , the point (x, y) is a point on this disc with radius $\sin \theta$. As we vary ϕ , this point describes a circle around the origin. Thus as $\sin \theta$ increases from 0 to 1, we have successively larger circles up to a circle with radius a .

To investigate the curvature of this metric, we can follow the procedure in Zee's Appendix I.5.1, where we evaluate the curvature given by R , defined as

$$R = \lim_{\text{radius} \rightarrow 0} \frac{6}{\text{radius}^2} \left(1 - \frac{\text{circumference}}{2\pi \text{radius}} \right) \quad (14)$$

where 'circumference' and 'radius' refer to a circle drawn around the point at which we wish to find the curvature.

Consider the origin in our current example. The distance from the origin to a circle of radius $\sin \epsilon$ is the distance measured along a curve of constant θ (since θ describes the radius as explained above). So

$$\text{radius} = \int_0^\epsilon \rho(r=0, \theta) d\theta = a \int_0^\epsilon \cos \theta d\theta \quad (15)$$

$$= a \sin \epsilon \quad (16)$$

The circumference of this circle is the length of the curve with radius $a \sin \epsilon$ as ϕ goes from 0 to 2π . That is

$$\text{circumference} = \int_0^{2\pi} a \sin \epsilon d\phi = 2\pi a \sin \epsilon \quad (17)$$

The curvature from 14 is then

$$R = \lim_{\epsilon \rightarrow 0} \frac{6}{a^2 \sin^2 \epsilon} \left(1 - \frac{2\pi a \sin \epsilon}{2\pi a \sin \epsilon} \right) = 0 \quad (18)$$

Thus the space is flat at the origin.

To study lines of fixed θ and ϕ (I'm assuming he means having both these fixed at the same time), we can play with the defining equations 12. We have

$$r = \frac{z}{\cos \theta} \quad (19)$$

so

$$x^2 = \left(\frac{z^2}{\cos^2 \theta} + a^2 \right) \sin^2 \theta \cos^2 \phi \quad (20)$$

$$y^2 = \left(\frac{z^2}{\cos^2 \theta} + a^2 \right) \sin^2 \theta \sin^2 \phi \quad (21)$$

Therefore

$$\frac{x^2}{\cos^2 \phi} - \frac{y^2}{\sin^2 \phi} = 0 \quad (22)$$

$$y = \pm x \tan \phi \quad (23)$$

Thus for a fixed value of ϕ , the plot of y versus x is a straight line.

We also have

$$\frac{z^2}{\cos^2 \theta} = \frac{x^2 + y^2}{\sin^2 \theta} - a^2 \quad (24)$$

$$= \frac{x^2}{\sin^2 \theta} (1 + \tan^2 \phi) - a^2 \quad (25)$$

$$= \frac{x^2}{\sin^2 \theta \cos^2 \phi} - a^2 \quad (26)$$

Rearranging, we have

$$\frac{x^2}{\sin^2 \theta \cos^2 \phi} - \frac{z^2}{\cos^2 \theta} = a^2 \quad (27)$$

For fixed θ , ϕ and a this is the equation of a hyperbola, with asymptotes given by

$$x = \pm \frac{\tan \theta}{\cos \phi} z \quad (28)$$

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