

## INTEGRAL OF A VECTOR FIELD OVER A SPHERE

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References: Kip S. Thorne & Roger D. Blandford, *Modern Classical Physics*, Princeton University Press (2017). Exercise 1.11.

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Suppose we want to integrate the vector field

$$\mathbf{A} = z\mathbf{e}_z \quad (1)$$

over the surface of a sphere of radius  $a$ . That is, we want

$$\int \mathbf{A} \cdot d\boldsymbol{\Sigma} \quad (2)$$

where  $d\boldsymbol{\Sigma}$  is an outward-pointing surface element on the sphere.

To do this, we introduce spherical coordinates  $\theta, \phi$  on the surface of the sphere.

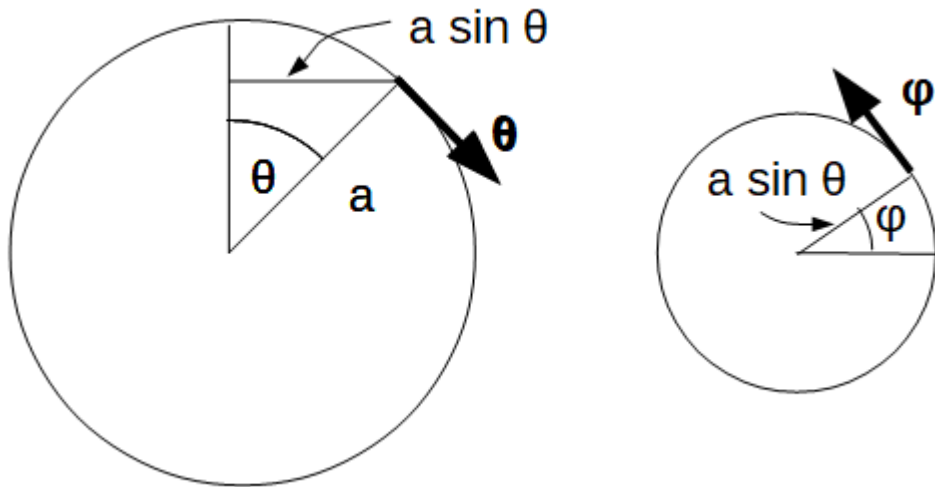


FIGURE 1. Spherical coordinates on a sphere. The LHS shows a vertical cross section through the poles. The RHS shows a horizontal cross section at angle  $\theta$ .

As usual, the angle  $\theta$  is the polar angle measured from the north pole (top) of the sphere, and  $\phi$  is the azimuthal angle measured counterclockwise around the sphere (see Fig. 1). A surface element is composed of an infinitesimal displacement in the  $\theta$  direction times an infinitesimal displacement in the  $\phi$  direction. From the figure, we see that an infinitesimal angle  $d\theta$  produces a distance of  $a d\theta$ . The distance produced by  $d\phi$  depends on the latitude. On the RHS of the figure, we show a horizontal cross-section of the sphere at angle  $\theta$ , which has a radius of  $a \sin\theta$ . Thus a displacement of  $d\phi$  produces a distance of  $a \sin\theta d\phi$  on the surface.

To produce a vectorial surface element  $d\mathbf{\Sigma}$ , we want a vector that is perpendicular to the surface element and points outwards. If the unit vector in the  $\theta$  direction is  $\mathbf{e}_{\hat{\theta}}$  (shown as a bold-face  $\theta$  in the figure, as I couldn't figure out how to show  $\mathbf{e}_{\hat{\theta}}$  in the drawing package) and the unit vector in the  $\phi$  direction is  $\mathbf{e}_{\hat{\phi}}$  (shown as  $\phi$ ), then the cross product  $\mathbf{e}_{\hat{\theta}} \times \mathbf{e}_{\hat{\phi}}$  is a unit vector that points outwards. Thus we can get the required vector as

$$d\mathbf{\Sigma} = (a \mathbf{e}_{\hat{\theta}}) \times (a \sin\theta \mathbf{e}_{\hat{\phi}}) d\theta d\phi \quad (3)$$

$$= (\mathbf{e}_{\hat{\theta}} \times \mathbf{e}_{\hat{\phi}}) a^2 \sin\theta d\theta d\phi \quad (4)$$

$$= \epsilon(-, \mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\phi}}) a^2 \sin\theta d\theta d\phi \quad (5)$$

where  $\epsilon(-, \mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\phi}})$  is the Levi-Civita tensor, with the first slot unoccupied, so that its components form a vector, with components

$$\epsilon(-, \mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\phi}})_i = (\mathbf{e}_{\hat{\theta}} \times \mathbf{e}_{\hat{\phi}})_i \quad (6)$$

To do the integral 2, we need the unit vector  $\mathbf{e}_z$  in terms of the spherical unit vectors.

From Fig. 2 we see that we can write

$$\mathbf{e}_z = \cos\theta \mathbf{e}_{\hat{r}} - \sin\theta \mathbf{e}_{\hat{\theta}} \quad (7)$$

This follows from the figure, since the projection of  $\mathbf{e}_z$  on  $\mathbf{e}_{\hat{r}}$  is  $\cos\theta$ . The projection of  $\mathbf{e}_z$  on  $\mathbf{e}_{\hat{\theta}}$  is the red dashed line in the figure, which is  $\sin\theta$ , and is in the opposite direction to the vector  $\mathbf{e}_{\hat{\theta}}$ . Thus we get 7.

The quantity  $z$  in 1 is the vertical distance measured from the centre of the sphere, so it ranges from  $z = -a$  at the south pole to  $z = +a$  at the north pole, and is given by

$$z = a \cos\theta \quad (8)$$

Since

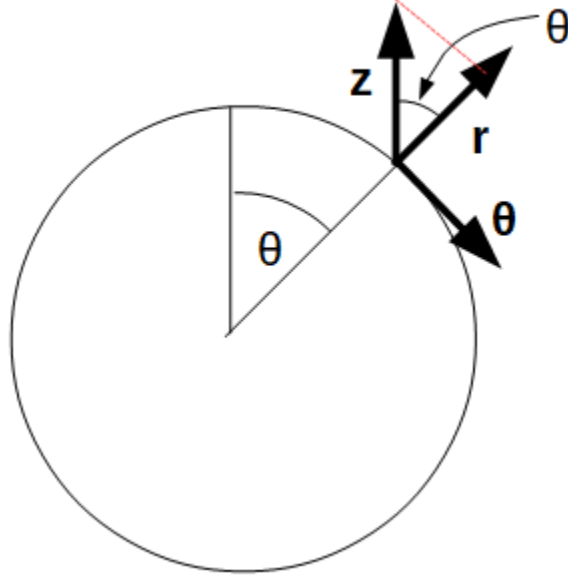


FIGURE 2. Unit vector  $e_z$  (labelled bold  $z$  in the diagram) in terms of the spherical unit vectors.

$$\mathbf{e}_{\hat{\theta}} \times \mathbf{e}_{\hat{\phi}} = \mathbf{e}_{\hat{r}} \quad (9)$$

and

$$\mathbf{e}_{\hat{r}} \cdot \mathbf{e}_{\hat{\theta}} = 0 \quad (10)$$

we have

$$\mathbf{A} \cdot d\boldsymbol{\Sigma} = a \cos \theta (\cos \theta \mathbf{e}_{\hat{r}} - \sin \theta \mathbf{e}_{\hat{\theta}}) \cdot \boldsymbol{\epsilon}(-, \mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\phi}}) a^2 \sin \theta d\theta d\phi \quad (11)$$

$$= a^2 \cos \theta \sin \theta \left[ \cos \theta \boldsymbol{\epsilon}(\mathbf{e}_{\hat{r}}, \mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\phi}}) - \sin \theta \boldsymbol{\epsilon}(\mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\phi}}) \right] d\theta d\phi \quad (12)$$

$$= a^3 \cos^2 \theta \sin \theta d\theta d\phi \quad (13)$$

Here we've used the property of the Levi-Civita tensor in 3-d:

$$\boldsymbol{\epsilon}(\mathbf{A}, \mathbf{B}, \mathbf{C}) \boldsymbol{\epsilon} = \mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) \quad (14)$$

The quantity  $\boldsymbol{\epsilon}(\mathbf{e}_{\hat{r}}, \mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\phi}}) = 1$  because it's the volume of a parallelepiped with 3 orthonormal edges, so its volume is 1. The quantity  $\boldsymbol{\epsilon}(\mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\theta}}, \mathbf{e}_{\hat{\phi}}) = 0$

because  $\epsilon$  is anti-symmetric, so repeating the vector  $e_{\hat{\theta}}$  in two slots gives zero.

Integrating 13 over the sphere gives us

$$\int \mathbf{A} \cdot d\mathbf{\Sigma} = \int_0^{2\pi} \int_0^{\pi} a^3 \cos^2 \theta \sin \theta \, d\theta \, d\phi \quad (15)$$

$$= 2\pi a^3 \left( -\frac{1}{3} \cos^3 \theta \right) \Big|_0^{\pi} \quad (16)$$

$$= \frac{4\pi a^3}{3} \quad (17)$$

which is the volume of the sphere.

I'm not sure how to justify this pictorially, but we can observe that applying Gauss's theorem to 2 we have, since  $\nabla \cdot \mathbf{A} = A_{i,i} = 1$  from 1

$$\int_S \mathbf{A} \cdot d\mathbf{\Sigma} = \int_V \nabla \cdot \mathbf{A} \, d^3x \quad (18)$$

$$= \int_V (1) \, d^3x \quad (19)$$

$$= \frac{4\pi a^3}{3} \quad (20)$$