

## ANTISYMMETRY OF THE ELECTROMAGNETIC FIELD TENSOR

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References: Kip S. Thorne & Roger D. Blandford, *Modern Classical Physics*, Princeton University Press (2017). Exercise 2.3.

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In their eqn 2.17, T&B show that the four-momentum  $\vec{p}$  must always be orthogonal to the four-force  $\vec{F}$  in the sense that

$$\vec{p} \cdot \vec{F} = 0 \quad (1)$$

Note that this is a 4-dimensional inner product and uses relativistic flat-space metric, so it's equivalent to (in components)

$$\eta_{jk} p^j F^k = 0 \quad (2)$$

In section 2.4.2, they derive the form of the electromagnetic field tensor, and show that it is a rank-2 tensor  $F$  with the property

$$F(\vec{u}, \vec{u}) = 0 \quad (3)$$

where  $\vec{u}$  is the timelike 4-velocity of the test charge.

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Ex. 2.3. We are to show that 3 is true if and only if  $F$  is antisymmetric. The 'if' part is trivial, since if  $F$  is antisymmetric, then swapping the two vectors in its arguments gives the negative of the original, so if the two vectors are the same, then we have

$$F(\vec{u}, \vec{u}) = -F(\vec{u}, \vec{u}) = 0 \quad (4)$$

We therefore need to show that if 3 is true, then  $F$  must be antisymmetric.

First, we can write a general rank-2 tensor as the sum of a symmetric tensor  $S$  and an antisymmetric tensor  $A$ . We have

$$F(\vec{a}, \vec{b}) = A(\vec{a}, \vec{b}) + S(\vec{a}, \vec{b}) \quad (5)$$

Swapping the vectors in the argument and using the symmetry and antisymmetry gives us

$$F(\vec{b}, \vec{a}) = A(\vec{b}, \vec{a}) + S(\vec{b}, \vec{a}) \quad (6)$$

$$= -A(\vec{a}, \vec{b}) + S(\vec{a}, \vec{b}) \quad (7)$$

Combining 5 and 7 we have

$$A(\vec{a}, \vec{b}) = \frac{1}{2} (F(\vec{a}, \vec{b}) - F(\vec{b}, \vec{a})) \quad (8)$$

$$S(\vec{a}, \vec{b}) = \frac{1}{2} (F(\vec{a}, \vec{b}) + F(\vec{b}, \vec{a})) \quad (9)$$

Thus we can always decompose a general tensor  $F$  into a symmetric and antisymmetric part. The antisymmetric part satisfies

$$A(\vec{u}, \vec{u}) = 0 \quad (10)$$

for the reason given above. We know from 3 and 5 that  $S(\vec{u}, \vec{u}) = 0$  for timelike  $\vec{u}$ . We would like to show that

We want to show that 3 is true for all timelike vectors  $\vec{u}$ . Let  $\vec{a}$  be a timelike vector and  $\vec{b}$  be an arbitrary (not necessarily timelike) vector. We define

$$\vec{A}_{\pm} \equiv \vec{a} \pm \epsilon \vec{b} \quad (11)$$

where  $\epsilon$  is small enough that both  $\vec{A}_{\pm}$  are still timelike. Using the linearity of tensors, we have

$$S(\vec{A}_+, \vec{A}_+) = S(\vec{a} + \epsilon \vec{b}, \vec{a} + \epsilon \vec{b}) \quad (12)$$

$$= S(\vec{a} + \epsilon \vec{b}, \vec{a}) + \epsilon S(\vec{a} + \epsilon \vec{b}, \vec{b}) \quad (13)$$

$$= S(\vec{a}, \vec{a}) + \epsilon S(\vec{b}, \vec{a}) + \epsilon S(\vec{a}, \vec{b}) + \epsilon^2 S(\vec{b}, \vec{b}) \quad (14)$$

$$= S(\vec{a}, \vec{a}) + 2\epsilon S(\vec{a}, \vec{b}) + \epsilon^2 S(\vec{b}, \vec{b}) \quad (15)$$

where the last line follows because  $S$  is symmetric, so

$$S(\vec{b}, \vec{a}) = S(\vec{a}, \vec{b}) \quad (16)$$

Similarly, we have

$$S(\vec{A}_-, \vec{A}_-) = S(\vec{a} - \epsilon\vec{b}, \vec{a} - \epsilon\vec{b}) \quad (17)$$

$$= S(\vec{a} - \epsilon\vec{b}, \vec{a}) - \epsilon S(\vec{a} - \epsilon\vec{b}, \vec{b}) \quad (18)$$

$$= S(\vec{a}, \vec{a}) - \epsilon S(\vec{b}, \vec{a}) - \epsilon S(\vec{a}, \vec{b}) + \epsilon^2 S(\vec{b}, \vec{b}) \quad (19)$$

$$= S(\vec{a}, \vec{a}) - 2\epsilon S(\vec{a}, \vec{b}) + \epsilon^2 S(\vec{b}, \vec{b}) \quad (20)$$

Since we require  $S(\vec{u}, \vec{u}) = 0$  for all timelike vectors  $\vec{u}$ , and  $\vec{A}_\pm$  and  $\vec{a}$  are all timelike vectors, then we have

$$S(\vec{A}_+, \vec{A}_+) = S(\vec{A}_-, \vec{A}_-) = S(\vec{a}, \vec{a}) = 0 \quad (21)$$

Thus 15 and 20 become

$$2S(\vec{a}, \vec{b}) + \epsilon S(\vec{b}, \vec{b}) = 0 \quad (22)$$

$$-2S(\vec{a}, \vec{b}) + \epsilon S(\vec{b}, \vec{b}) = 0 \quad (23)$$

Adding these two equations gives us

$$S(\vec{b}, \vec{b}) = 0 \quad (24)$$

for *all* (not just timelike) vectors  $\vec{b}$ . Plugging this back into 22 gives us

$$S(\vec{a}, \vec{b}) = 0 \quad (25)$$

This shows that  $S$  is zero when one vector is timelike and the other is arbitrary. To show that  $S$  is still zero if neither vector is timelike, we can repeat the derivation above, but this time we start with a vector  $\vec{c}$  that is *not* timelike and define

$$\vec{C}_\pm \equiv \vec{c} \pm \epsilon\vec{d} \quad (26)$$

where  $\vec{d}$  is arbitrary, and  $\epsilon$  is small enough that both  $\vec{C}_\pm$  are not timelike. Since we know from 24 that  $S$  is zero whenever its two arguments are the same, we can apply this to  $S(\vec{C}_\pm, \vec{C}_\pm)$ ,  $S(\vec{c}, \vec{c})$  and  $S(\vec{d}, \vec{d})$  to show that

$$S(\vec{c}, \vec{d}) = 0 \quad (27)$$

That is,  $S$  is zero when one of its arguments is not timelike and the other is arbitrary. This, combined with 25 shows that  $S$  is zero for any two vectors as its arguments, and thus

$$F(\vec{A}, \vec{B}) = A(\vec{A}, \vec{B}) = -A(\vec{B}, \vec{A}) \quad (28)$$

so that  $F$  is antisymmetric. As we've seen earlier, the explicit form of the tensor in components is

$$F^{ij} = \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{bmatrix} \quad (29)$$

and is indeed antisymmetric.