

TRANSFORMATIONS OF GRADIENT AND LAPLACIAN

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References: Anthony Zee, *Einstein Gravity in a Nutshell*, (Princeton University Press, 2013) - Chapter I.4, Problem 1.

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I've done a lot of posts involving tensors, but Zee's approach is a simpler way of looking at them, so it's worth revisiting the definition of a tensor. Zee's definition of a tensor is that it is "something that transforms like a tensor". Of course, in order for this definition to make sense, we need to know how a tensor transforms. If we have a tensor with 2 indices such as T^{ij} , then it must transform under a rotation according to (using the summation convention):

$$T'^{ij} = R^{ik} R^{jl} T^{kl} \quad (1)$$

[At this stage, we're not distinguishing between upper and lower indices; that will come later.] Thus a vector is a tensor with a single index.

Example 1. The gradient of a scalar is a tensor (actually a vector), as we can see using the following.

$$(\nabla\phi)^i \equiv \frac{\partial\phi}{\partial x^i} \quad (2)$$

If we rotate the coordinate system, then the new coordinates are related to the old ones by

$$x'^i = R^{ij} x^j \quad (3)$$

Thus we have

$$\frac{\partial x'^i}{\partial x^j} = R^{ij} \quad (4)$$

Because the inverse of a rotation matrix is also its transpose, we have

$$x^i = (R^{-1})^{ij} x'^j \quad (5)$$

$$= (R^T)^{ij} x'^j \quad (6)$$

$$= R^{ji} x'^j \quad (7)$$

Therefore

$$\frac{\partial x^i}{\partial x'^j} = R^{ji} \quad (8)$$

Using the chain rule

$$\frac{\partial}{\partial x'^i} = \frac{\partial x^j}{\partial x'^i} \frac{\partial}{\partial x^j} \quad (9)$$

$$= R^{ij} \frac{\partial}{\partial x^j} \quad (10)$$

Therefore the rotation matrix is given by

$$R^{ij} = \frac{\partial x^j}{\partial x'^i} \quad (11)$$

The rotated gradient is thus

$$(\nabla' \phi)^i = \frac{\partial \phi}{\partial x'^i} \quad (12)$$

$$= \frac{\partial x^j}{\partial x'^i} \frac{\partial \phi}{\partial x^j} \quad (13)$$

$$= R^{ij} \frac{\partial \phi}{\partial x^j} \quad (14)$$

$$= R^{ij} (\nabla \phi)^j \quad (15)$$

The gradient therefore transforms like a tensor so it is a tensor.

Example 2. What about the square of the gradient of a scalar? We have

$$(\nabla \phi) \cdot (\nabla \phi) = \sum_i \left(\frac{\partial \phi}{\partial x^i} \right)^2 \quad (16)$$

Rotating the coordinates gives

$$(\nabla' \phi) \cdot (\nabla' \phi) = \sum_i \left(\frac{\partial \phi}{\partial x'^i} \right)^2 \quad (17)$$

$$= R^{ij} \frac{\partial \phi}{\partial x^j} R^{ik} \frac{\partial \phi}{\partial x^k} \quad (18)$$

We can now use the fact that $R^T = R^{-1}$ so $R^{ij} = (R^{-1})^{ji}$:

$$(\nabla'\phi) \cdot (\nabla'\phi) = (R^{-1})^{ji} R^{ik} \frac{\partial\phi}{\partial x^j} \frac{\partial\phi}{\partial x^k} \quad (19)$$

$$= \delta^{jk} \frac{\partial\phi}{\partial x^j} \frac{\partial\phi}{\partial x^k} \quad (20)$$

$$= \sum_j \left(\frac{\partial\phi}{\partial x^j} \right)^2 \quad (21)$$

$$= (\nabla\phi) \cdot (\nabla\phi) \quad (22)$$

Thus $(\nabla\phi) \cdot (\nabla\phi)$ is invariant under rotation, so it's a scalar.

Example 3. The Laplacian of a scalar is also a scalar. The Laplacian is defined as

$$\nabla^2\phi \equiv \sum_i \frac{\partial^2\phi}{(\partial x^i)^2} \quad (23)$$

$$= \frac{\partial}{\partial x^i} \left(\frac{\partial\phi}{\partial x^i} \right) \quad (24)$$

Under rotation, we have

$$\nabla'^2\phi = \frac{\partial}{\partial x'^i} \left(\frac{\partial\phi}{\partial x'^i} \right) \quad (25)$$

$$= R^{ij} \frac{\partial}{\partial x^j} \left(R^{ik} \frac{\partial\phi}{\partial x^k} \right) \quad (26)$$

$$= (R^{-1})^{ji} R^{ik} \frac{\partial}{\partial x^j} \left(\frac{\partial\phi}{\partial x^k} \right) \quad (27)$$

$$= \delta^{jk} \frac{\partial}{\partial x^j} \left(\frac{\partial\phi}{\partial x^k} \right) \quad (28)$$

$$= \frac{\partial}{\partial x^j} \left(\frac{\partial\phi}{\partial x^j} \right) \quad (29)$$

$$= \nabla^2\phi \quad (30)$$

Note that the rotation matrix R is a constant with respect to $\frac{\partial}{\partial x^j}$ since we're considering a fixed rotation. The derivative measures how the scalar field ϕ varies as we move from one point to another, whereas R relates one set of fixed coordinates to another set of fixed coordinates.

Thus $\nabla^2\phi$ is invariant under rotation, so it's a scalar.

PINGBACKS

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